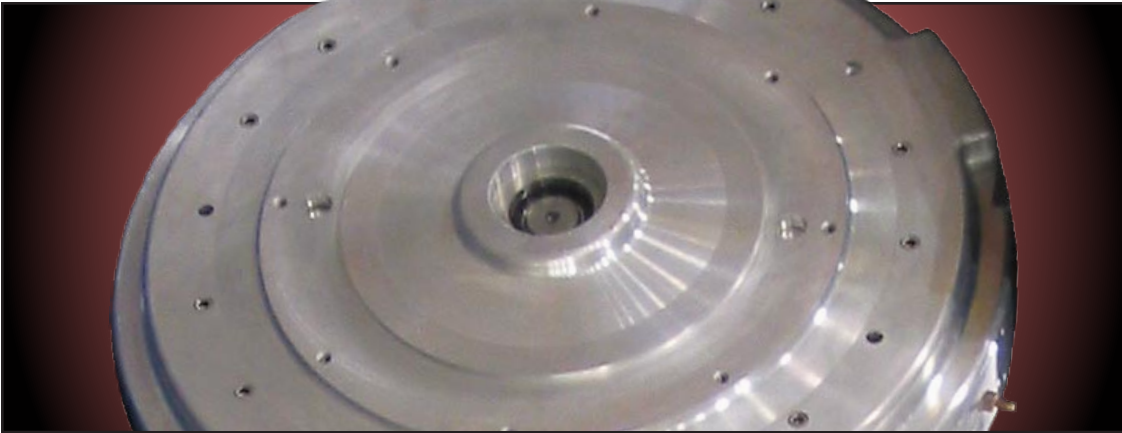


# E813

## Axial Flux BLDC Motor



The E813 motor is part of a permanent-magnet motor system designed for power generation applications where high system efficiency is important. Developed for a customer for use in high-efficiency distributed-power systems, the E813 was designed to give the competitive edge necessary in this relatively new and highly competitive field.

In addition to the E813, a number of other coil configurations have been studied in the same frame size – including multi-slice versions and high peak-torque versions – for a variety of industrial and military applications. The family of E813 motor designs currently under development with government and commercial partners will offer a broad range of possible system configurations for both high-efficiency and high-torque speed-servo applications.

The specifications provided here illustrate some of the E813's capabilities. Especially noteworthy is its high efficiency over a very large operating range. Low-speed, high-torque versions of this motor are currently under development for direct-drive position-servos for naval applications.

Contact a Lynx applications engineer to determine if there is an 813 mm SEMA design that can meet your needs.

### Typical Applications

- Power Generation
- Servo Applications
- Precision Robotics
- Marine Propulsion
- Weapons Turrets
- Compressors / Blowers

### Application Information

- Requires 3-phase PWM inverter, available through Lynx partners
- Performance ratings based on 130°C winding, 40°C ambient air
- Developed for use in high-efficiency PM synchronous distributed power generation units

### Standard Features

- Brushless axial flux design
- Use of patented SEMA coil provides superior power density
- Ironless design eliminates cogging torque
- Extremely linear torque constant independent of speed



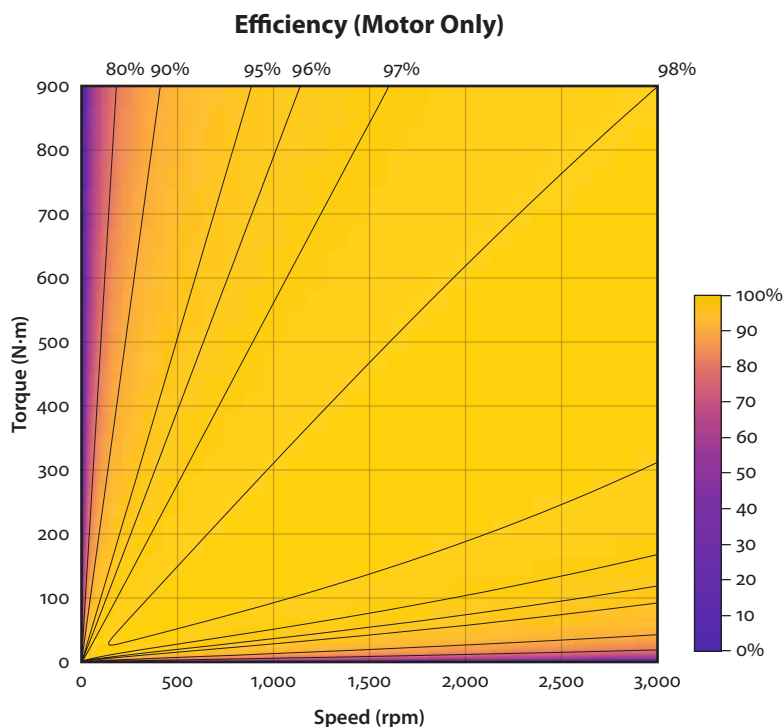
**Lynx Motion Technology**

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# E813

Parameter	Symbol	SI	English
<b>Continuous Ratings</b>			
Supply Voltage (DC bus)	$V_s$	<b>850</b> V <sub>DC</sub>	<b>850</b> V <sub>DC</sub>
Voltage (line to line)	$V_{L-L}$	<b>574</b> V <sub>AC</sub> (pk-pk)	<b>574</b> V <sub>AC</sub> (pk-pk)
Speed	$S$	<b>2,750</b> rpm	<b>2,750</b> rpm
Torque	$T_c$	<b>450</b> N·m	<b>332</b> lbf·ft
Current	$I$	<b>119</b> A <sub>rms</sub>	<b>119</b> A <sub>rms</sub>
Power	$P_{out}$	<b>130</b> kW	<b>174</b> hp
<b>Peak Ratings</b>			
Peak Torque <sup>1</sup>	$T_{pk}$	<b>900</b> N·m	<b>664</b> lbf·ft
Peak Current <sup>1</sup>	$I_{pk}$	<b>238</b> A	<b>238</b> A
<b>Motor Constants</b>			
Torque Constant	$K_T$	<b>3.78</b> N·m/A	<b>2.79</b> lbf·ft/A
Back EMF Constant (phase to neutral)	$K_E$	<b>209</b> V <sub>rms</sub> /krpm	<b>209</b> V <sub>rms</sub> /krpm
Electrical Time Constant	$\tau_e$	<b>1.66</b> $\mu$ s	<b>1.66</b> $\mu$ s
<b>Electrical Aspects</b>			
Resistance (cold, per phase)	$R$	<b>26.5</b> m $\Omega$	<b>26.5</b> m $\Omega$
Inductance (per phase)	$L$	<b>44</b> $\mu$ H	<b>44</b> $\mu$ H
<b>Mechanical Aspects</b>			
Inertia (rotor only)	$J_r$	<b>9.16</b> kg·m <sup>2</sup>	<b>6.76</b> lbf·ft·s <sup>2</sup>
Mass (entire motor)	$m$	<b>295</b> kg	<b>650</b> lb
Number of Poles	—	<b>28</b> poles	<b>28</b> poles
Motor Diameter (actual)	AC	<b>813</b> mm	<b>32</b> in.

<sup>1</sup> Peak ratings are based on operational capabilities of existing inverter. Higher peak torques are possible using a different controller. Contact a Lynx engineer for details.



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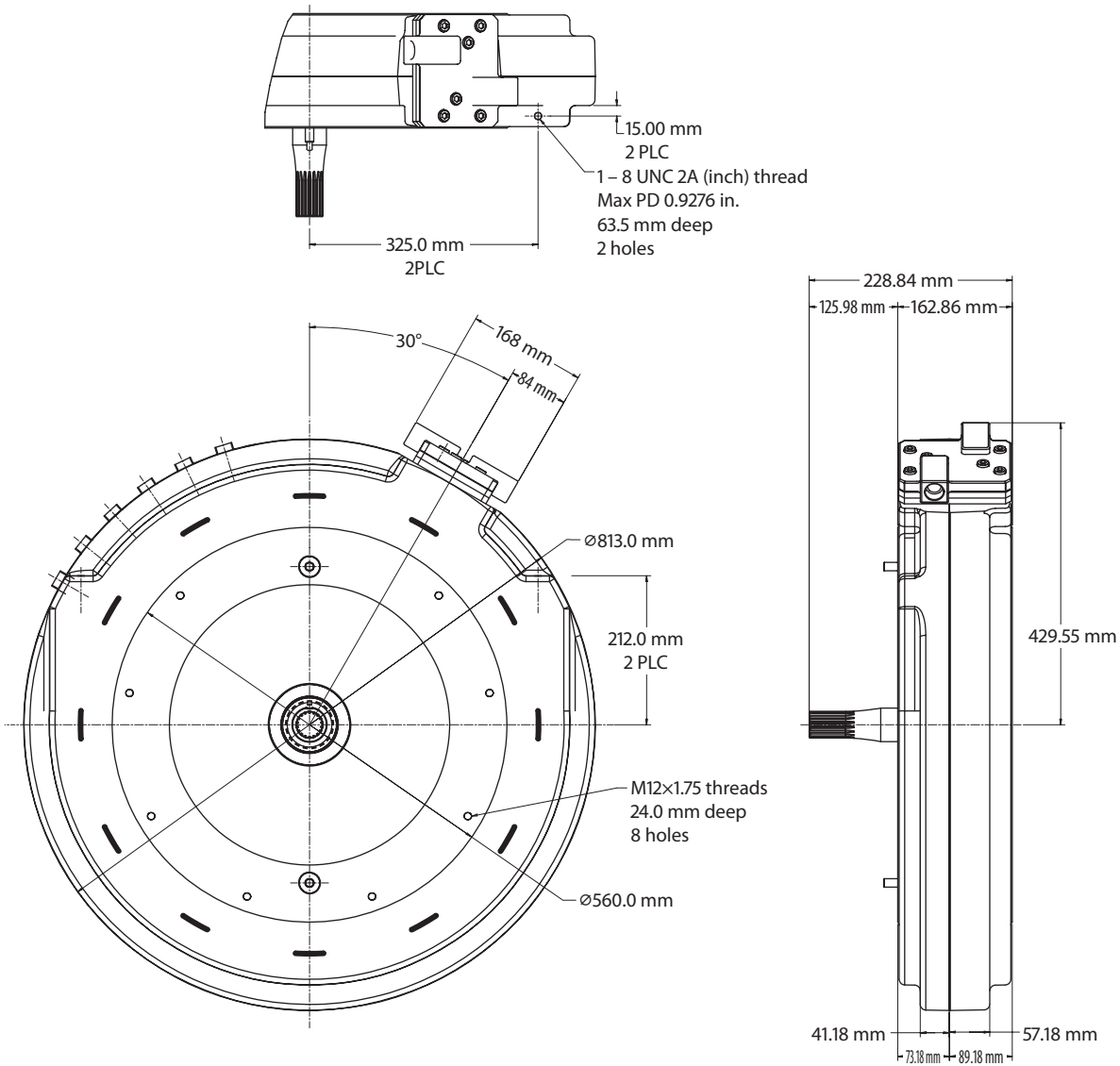
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